

## A Class of Estimators for Mean of Symmetrical Population when the Variance is not known

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### SUMMARY

A class of estimators of population mean ( $\mu$ ) when the variance ( $\sigma^2$ ) is unknown, is proposed in case of symmetrical populations. Bias and mean squared error are found for the class. Various estimators are shown to belong to the class and sub-class of optimum estimators in the sense of having minimum mean squared error is found.

*Key words* : Class of estimators, Coefficient of variation, Mean square error, Unknown variance.

### Introduction

Utilising known square of coefficient of variation  $C^2 = \left( \frac{\sigma^2}{\mu^2} \right)$ , Searles [2] proposed an improved estimator of population mean  $\mu$ ; but when  $C^2$  is unknown, the problem of estimation consists of estimators using the estimates of  $C^2$  given by

$$\hat{C}^2 = \frac{s^2}{\bar{y}^2} \text{ or } \hat{C}^2 = \frac{s^2}{\bar{y}^2} \left( 1 - \frac{s^2}{n \bar{y}^2} \right)^{-1}$$

where  $\bar{y} = \frac{1}{n} \sum_{i=1}^n y_i$  and  $s^2 = \frac{1}{(n-1)} \sum_{i=1}^n (y_i - \bar{y})^2$  for the values  $y_1, y_2, \dots, y_n$  of a random sample of size  $n$ .

In this paper, with  $u = \frac{s^2}{n \bar{y}^2}$ , the following class of estimators are proposed for population mean  $\mu$

$$t = f \left( \bar{y}, \frac{s^2}{n \bar{y}^2} \right) = f(\bar{y}, u)$$

where  $f(\bar{y}, u)$  satisfying the validity conditions of Taylor's series expansion, is the function of  $(\bar{y}, u)$  such that  $f(\mu, 0) = \mu$ , first order partial derivative

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$f_1' = \frac{\delta f(\bar{y}, u)}{\delta \bar{y}} \Big|_{(\mu, 0)} = 1$  second order partial derivative  $\frac{\delta^2 f(\bar{y}, u)}{\delta \bar{y}^2} = 0$  and  
 second order partial derivative  $f_{12}'' = \frac{\delta^2 f(\bar{y}, u)}{\delta \bar{y} \delta u} \Big|_{(\mu, 0)} = \frac{f_2' \delta}{\mu}$  (with  $f_2'$  being  
 the first order of  $f(\bar{y}, u)$  with respect to  $u$  at the point  $(\mu, 0)$  and  $\delta$  taking one  
 of the two values 'zero and unity' depending upon the particular form of an  
 estimator. For example, for the estimator  $\bar{y} + k u$ ,  $\delta$  takes values zero whereas  
 for the estimator  $\bar{y}(1 - \mu)$ ,  $\delta = 1$ ).

Some special cases of the generalized estimator  $t$  when  $\sigma^2$  is unknown and  $k, g, \alpha$  being the characterising scalars, are

$$(1) \quad t_1 = \bar{y} + k \frac{s^2}{n y^2} = \bar{y} + k u$$

$$(2) \quad t_2 = \bar{y} + k \frac{s^2}{n y^2} \left( 1 + g \frac{s^2}{n y^2} \right) \\ = \bar{y} + k u (1 + g u)$$

$$(3) \quad t_3 = \bar{y} \left[ 1 + \frac{k s^2}{n y^2} \left( 1 + g \frac{s^2}{n y^2} \right)^\alpha \right] \text{ by Singh [3]} \\ = \bar{y} \left[ 1 + k u (1 + g u)^{-\alpha} \right]$$

$$(4) \quad t_4 = \bar{y} \left[ 1 - \frac{s^2}{n y^2} \left( 1 + \frac{s^2}{n y^2} \right)^{-1} \right] \text{ by Srivastava [4, 5]} \\ = \bar{y} \left[ 1 - u (1 + u)^{-1} \right]$$

$$(5) \quad t_5 = \bar{y} \left( 1 - \frac{s^2}{n y^2} \right) \text{ by Srivastava [4, 5]} \\ = \bar{y} (1 - u).$$

$$(6) \quad t_6 = \bar{y} \left[ 1 + \frac{k s^2}{n y^2} \left( 1 - \frac{k s^2}{n y^2} \right)^{-1} \right] \text{ by Thompson [9]} \\ = \bar{y} \left[ 1 + k u (1 - k u)^{-1} \right]$$

$$(7) \quad t_7 = \bar{y} \left( 1 + g \frac{s^2}{n y^2} \right) \text{ by Upadhyaya and Srivastava [10]} \\ = \bar{y} (1 + u)$$

$$(8) \quad t_8 = \bar{y} \left[ 1 + \frac{s^2}{n \bar{y}^2} \left( 1 + \frac{s^2}{n \bar{y}^2} \right)^{-1} \right] \text{ by Sahai and Ray [1]}$$

$$= \bar{y} [1 + u (1 + u)^{-1}]$$

$$(9) \quad t_9 = \bar{y} \left[ 1 + \frac{s^2}{n \bar{y}^2} \left( 1 + \frac{s^2}{n \bar{y}^2} \right)^{-1} \right] \text{ by Srivastava and Banarsi [6]}$$

$$= \bar{y} [1 + u (1 + u)^{-2}]$$

$$(10) \quad t_{10} = \bar{y} \left[ 1 + \frac{k s^2}{n \bar{y}^2} \left( 1 + \frac{g s^2}{n \bar{y}^2} \right)^{-1} \right] \text{ by Srivastava and Bhatnagar [7]}$$

$$= [1 + k u (1 + g u)^{-1}]$$

$$(11) \quad t_{11} = \bar{y} \left[ 1 + \frac{s^2}{n \bar{y}^2} \left( 1 - \frac{s^2}{n \bar{y}^2} \right)^{-1} \right] \text{ by Srivastava and Dwivedi [8]}$$

$$= \bar{y} [1 + u (1 - u)^{-1}]$$

where various forms of the function  $f(\bar{y}, u)$  are given by the expressions on right hand sides of (1) to (11) in terms of  $\bar{y}$  and  $u$ .

It may be mentioned here that all the estimators listed from (1) to (11) belong to the class  $t$  and satisfy the condition  $f(\mu, 0) = \mu$  with  $f'_1 = 1$  and  $f''_{12} = f'_2 \delta / \mu$ ,  $\delta = 1$  or  $0$ .

## 2. Bias and Mean square error of $t$

To find the bias and mean square error (MSE) of  $t$  upto terms of order  $O(n^{-2})$ , let

$$\bar{y} = \mu + z \text{ and } s^2 = \sigma^2 + v \quad (2.1)$$

where  $z$  and  $v$  are of order  $O(n^{-1/2})$  with  $E(z) = E(v) = 0$ , and  $E(z)^2 = \frac{\sigma^2}{n} = \frac{\mu^2 C^2}{n}$ .

With  $\bar{y}^* = \mu + \theta(\bar{y} - \mu)$  and  $u^* = \theta u$ ,  $0 < \theta < 1$ , expanding  $t = f(\bar{y}, u)$  in third order Taylor's series about the point  $\mu, 0$ , we have

$$\begin{aligned}
 t = & f(\mu, 0) + (\bar{y} - \mu) \left. \frac{\delta f(\bar{y}, u)}{\delta \bar{y}} \right|_{(\mu, 0)} + u \left. \frac{\delta f(\bar{y}, u)}{\delta u} \right|_{(\mu, 0)} \\
 & + \frac{1}{2!} \left\{ (\bar{y} - \mu)^2 \left. \frac{\delta^2 f(\bar{y}, u)}{\delta \bar{y}^2} \right|_{(\mu, 0)} + 2(\bar{y} - \mu) u \left. \frac{\delta^2 f(\bar{y}, u)}{\delta \bar{y} \delta u} \right|_{(\mu, 0)} \right. \\
 & \left. + u^2 \left. \frac{\delta^2 f(\bar{y}, u)}{\delta u^2} \right|_{(\mu, 0)} \right\} + \frac{1}{3!} \left\{ (\bar{y} - \mu) \frac{\delta}{\delta \bar{y}} + u \frac{\delta}{\delta u} \right\}^3 f(\bar{y}^*, u^*)
 \end{aligned}$$

Now, we have  $\left. \frac{\delta f(\bar{y}, u)}{\delta \bar{y}} \right|_{(\mu, 0)} = 1$ ,  $\left. \frac{\delta^2 f(\bar{y}, u)}{\delta \bar{y}^2} \right|_{(\mu, 0)} = 0$ ,

$\left. \frac{\delta^3 f(\bar{y}, u)}{\delta \bar{y}^3} \right|_{(\mu, 0)} = 0$ ,  $\left. \frac{\delta^3 f(\bar{y}, u)}{\delta \bar{y}^2 \delta u} \right|_{(\mu, 0)} = 0$ ; and further for  $\bar{y} - \mu = z$  and

$$\begin{aligned}
 \left[ \frac{z}{\mu} \right] < 1, u = \frac{s^2}{n \bar{y}^2} = \frac{\delta^2 (1 + v/\sigma^2)}{n \mu^2 \left(1 + \frac{z}{\mu}\right)^2} = \frac{C^2}{n} \left(1 + \frac{V}{\sigma^2}\right) \left(1 + \frac{z}{\mu}\right)^{-2} \\
 = \frac{C^2}{n} \left(1 + \frac{V}{\sigma^2}\right) \left(1 - \frac{2z}{\mu} + \dots\right)
 \end{aligned}$$

so that

$$\begin{aligned}
 t = & \mu + z + \frac{C^2}{n} \left(1 + \frac{V}{\sigma^2}\right) \left(1 - \frac{2z}{\mu} + \dots\right) f_2' \\
 & + \frac{1}{2!} \left\{ 0 + 2z \frac{C^2}{n} \left(1 + \frac{V}{\sigma^2}\right) \left(1 + \frac{z}{\mu}\right)^{-2} f_{12}'' \right. \\
 & \left. + \frac{C^4}{n^2} \left(1 + \frac{V}{\sigma^2}\right)^2 \left(1 + \frac{z}{\mu}\right)^{-4} f_2^{*4} \right\} + \frac{1}{3!} \left\{ 0 + 3(\bar{y} - \mu)^2 \right. \\
 & \left. \cdot u \frac{\delta^2 f(\bar{y}^*, u^*)}{\delta \bar{y}^{*2} \delta u^*} + 3(\bar{y} - \mu) u^2 \frac{\delta^3 f(\bar{y}^*, u^*)}{\delta \bar{y}^* \delta u^{*2}} \right. \\
 & \left. + u^3 \frac{\delta^3 f(\bar{y}^*, u^*)}{\delta u^{*3}} \right\}
 \end{aligned}$$

$$\begin{aligned}
&= \mu + z + \frac{C^2}{n} \left(1 - \frac{V}{\sigma^2}\right) \left(1 - \frac{2z}{\mu} + 3 \frac{z^2}{\mu^2} - 4 \frac{z^3}{\mu^3} + 5 \frac{z^5}{\mu^5} - \dots\right) f_2' \\
&+ \frac{1}{2!} \left\{ \frac{2z C^2}{n} \left(1 + \frac{V}{\sigma^2}\right) \left(1 - \frac{2z}{\mu} + \frac{3z^2}{\mu^2} - \frac{4z^3}{\mu^3} + \frac{5z^4}{\mu^4} - \dots\right) f_{12}'' \right. \\
&+ \frac{C^4}{n^2} \left(1 + \frac{V}{\sigma^2}\right)^2 \left(1 + \frac{z}{\mu}\right)^{-4} f_2'' \left. + \frac{1}{3!} \left\{ 0 + 3(\bar{y} - \mu)^2 \frac{u \sigma^2 f(y^*, u^*)}{\delta \bar{y}^{\sigma^2} \delta u^*} \right. \right. \\
&\left. \left. + 3(\bar{y} - \mu) u^2 \delta^3 \frac{f(\bar{y}^*, u^*)}{\delta \bar{y}^* \delta u^{*2}} + u^3 \delta^3 \frac{f(\bar{y}^*, u^*)}{\delta u^{*3}} \right\} \right. \\
&= \mu + z + \frac{1}{n} \left\{ \left( C^2 - 2C^2 \frac{z}{\mu} + \frac{V}{\mu^2} + 3C^2 \frac{z^2}{\mu^2} - \frac{2zV}{\mu^3} \right) - 4C^2 \frac{z^3}{\mu^3} \right. \\
&\left. + 3 \frac{z^2 V}{\mu^4} + 5C^2 \frac{z^4}{\mu^4} - 4 \frac{z^2 V}{\mu^6} + \dots \right\} f_2' + \frac{1}{n} \left\{ \left( C^2 z - 2C^2 \frac{z^2}{\mu} + \frac{zV}{\mu^2} \right) \right. \\
&\left. + 3C^2 \frac{z^3}{\mu^2} - 2 \frac{z^2 V}{\mu^3} - 4C^2 \frac{z^4}{\mu^3} \right. \\
&\left. + 3 \frac{z^2 V}{\mu^4} + 5C^2 \frac{z^5}{\mu^4} - 4 \frac{z^4 V}{\mu^5} + 5 \frac{z^5 V}{\mu^6} + \dots \right\} f_{12}'' \\
&+ \frac{C^4}{2n^2} \left(1 + \frac{V}{\sigma^2}\right)^2 \left(1 + \frac{z}{\mu}\right)^{-4} f_2'' + \frac{1}{3!} \left\{ 3(\bar{y} - \mu)^2 u \delta^3 \frac{f(\bar{y}^*, u^*)}{\delta \bar{y}^{\sigma^2} \delta u^*} \right. \\
&\left. + 3(\bar{y} - \mu) u^2 \frac{\delta^3 f(\bar{y}^*, u^*)}{\delta \bar{y}^* \delta u^{*2}} + u^3 \frac{\delta^3 f(\bar{y}^*, u^*)}{\delta \mu^{*3}} \right\} \quad (2.3)
\end{aligned}$$

Taking expectation in (2.3), to the terms of order 0 ( $n^{-2}$ ), for symmetrical populations, we have

$$\begin{aligned}
E(t) &= \mu + E \frac{C^2}{n} \left(1 + \frac{3z^2}{\mu^2}\right) f_2' - \frac{2z^2 C^2}{n \mu} f_{12}'' + \frac{C^4}{2n^2} f_2'' \\
&= \mu + \frac{C^2}{n} \left(1 + \frac{3C^2}{n}\right) f_2' - \frac{2\mu C^4}{n} f_{12}'' + \frac{C^4}{2n^2} f_2''
\end{aligned}$$

or Bias (t) = E (t) -  $\mu$

$$= \frac{C^2}{n} \left[ \left(1 + \frac{C^2}{n}\right) f_2' + \frac{2C^2}{n} (f_2' - \mu f_{12}'') + \frac{C^2}{2n} f_2'' \right] \quad (2.4)$$

Again, from (2.3), we have

$$\begin{aligned} \text{MSE}(t) &= E(t - \mu)^2 \\ &= E \left[ z + \frac{1}{n} \left\{ \left( C^2 - 2C^2 \frac{z}{\mu} + \frac{V}{\mu^2} + 3C^2 \frac{z^2}{\mu^2} - \frac{2zV}{\mu^3} \right) - 4C^2 \frac{z^3}{\mu^3} \right. \right. \\ &\quad \left. \left. + 3 \frac{z^2 V}{\mu^4} + 5C^2 \frac{z^4}{\mu^4} - 4 \frac{z^3 V}{\mu^5} + 5 \frac{z^4 V}{\mu^6} + \dots \right\} f_2' \right. \\ &\quad \left. + \frac{1}{n} \left\{ \left( C^2 z - 2C^2 \frac{z^2}{\mu} + \frac{zV}{\mu^2} \right) + 3C^2 \frac{z^3}{\mu^2} - \frac{2z^2 V}{\mu^3} - 4C^2 \frac{z^4}{\mu^3} \right. \right. \\ &\quad \left. \left. + 3 \frac{z^3 V}{\mu^4} + 5C^2 \frac{z^5}{\mu^4} - \frac{4z^4 V}{\mu^5} + \frac{5z^5 V}{\mu^6} + \dots \right\} f_{12}'' \right. \\ &\quad \left. + \frac{C^4}{2n^2} \left( 1 + \frac{V}{\sigma^2} \right)^2 \left( 1 + \frac{z}{\mu} \right)^{-4} f_2^2 \right. \\ &\quad \left. + \frac{1}{3!} \left[ 3(\bar{y} - \mu)^2 u \frac{\delta^3 f(\bar{y}^*, u^*)}{\delta \bar{y}^2 \delta u^*} + 3(\bar{y} - \mu) u^2 \frac{\delta^3 f(\bar{y}^*, u^*)}{\delta \bar{y}^* \delta u^{*2}} \right. \right. \\ &\quad \left. \left. + u^3 \frac{\delta^3 f(\bar{y}^*, u^*)}{\delta u^{*3}} \right] \right]^2 \end{aligned}$$

whence, upto terms of order  $O(n^{-2})$ , the mean square error of  $t$  is

$$\text{MSE}(t) = E \left[ z^2 + \frac{C^4}{n^2} (f_2')^2 + \frac{2z}{n} \left( C^2 - 2C^2 \frac{z}{\mu} + \frac{V}{\mu^2} \right) f_2^2 + 2 \frac{z^2}{n} C^2 f_{12}'' \right]$$

from which, for symmetrical populations, upto terms of order  $O(n^{-2})$ , the mean square of  $t$  is

$$\begin{aligned} \text{MSE}(t) &= \frac{\mu^2 C^2}{n} + \frac{C^4}{n^2} (f_2')^2 - 4\mu \frac{C^4}{n^2} f_2^2 + \frac{2\mu^2 C^4}{n^2} f_{12}'' \\ &= \frac{\mu^2 C^2}{n} \left[ 1 + \frac{C^2}{n} \left\{ \frac{(f_2')^2}{\mu^2} - \frac{4f_2'}{\mu} + \frac{2f_2' \delta}{\mu} \right\} \right] \end{aligned} \quad (2.5)$$

which is minimised for

$$f_2' = \mu(2 - \delta) \quad (2.6)$$

where  $\delta$  takes one of the two values '0 and 1' and the minimum mean square error is given by

$$\begin{aligned} \text{MSE}(t)_{\min} &= \frac{\mu^2 C^2}{n} \left[ 1 + \frac{C^2}{n} \{(2-\delta)^2 - 4(2-\delta) + 2(2-\delta)\delta\} \right] \\ &= \frac{\mu^2 C^2}{n} \left[ 1 - \frac{C^2}{n} (2-\delta)^2 \right] \end{aligned} \quad (2.7)$$

### 3. Concluding Remarks

- (a) From (2.6) and (2.7), the class of estimators  $t$  attains its minimum value for  $f_2' = \mu(2-\delta)$ ,  $\delta = \mu f_{12}''/f_2'$ , and the minimum mean square error is

$$\text{MSE}(t)_{\min} = \frac{\mu^2 C^2}{n} \left[ 1 - \frac{C^2}{n} (2-\delta)^2 \right] \quad (3.1)$$

Thus, any estimator from the class  $t$  cannot have mean square error less than the expression given by (3.1).

- (b) Bias, mean square error and the related results to the estimators listed in section 1 may easily be found as special cases of this study. For example, with  $k$ ,  $g$  and  $\alpha$  being the characterizing scalars for the estimator.

$$\begin{aligned} t_3 &= \bar{y} \left[ 1 + \frac{k s^2}{n \bar{y}^2} \left( 1 + \frac{g s^2}{n \bar{y}^2} \right)^{-\alpha} \right] \\ &= \bar{y} \left[ 1 + k u (1 + g u)^{-\alpha} \right] \end{aligned}$$

by Singh [3], we have  $f_{12}'' = k$ ,  $f_2' = k\mu$ ,  $\delta = \frac{\mu f_{12}''}{f_2'} = 1$  so that  $f_2' = \mu(2-\delta) = k\mu$  satisfying (2.6) gives the value of  $k=1$  for which MSE ( $t_3$ ) is minimised and the minimum mean square error

$$\text{MSE}(t_3)_{\min} = \frac{\mu^2 C^2}{n} \left( 1 - \frac{C^2}{n} \right) \quad (3.2)$$

is obtained from (3.1) by putting  $\delta = 1$ . Further, for the estimator  $t_3$ , we have  $f_2' = k\mu$ ,  $f_{12}'' = k$  and  $f_2'' = -2\alpha k g \mu$ , so that the bias of  $t_3$  from (2.4) is

$$\text{Bias}(t_3) = \frac{k\mu C^2}{n} \left[ 1 + \frac{C^2}{n} (1 - \alpha g) \right] \quad (3.3)$$



which, for  $k = g = 1$ , reduces to

$$\text{Bias}(t_3) = \frac{\mu C^2}{n} \left[ 1 - (\alpha - 1) \frac{C^2}{n} \right]. \quad (3.4)$$

It may be mentioned here that the expressions (3.2) and (3.4) are the same expressions as obtained by Singh [3]. Similarly, the results of all the estimators listed in section 1 may easily be shown to be special cases of those of the generalized estimator  $t$ .

- (c) For the estimators having  $f_{12}'' = 0$ , that is  $\delta = 0$ , we have from (2.7)

$$\text{MSE}(t)_{\min.} = \frac{\mu^2 C^2}{n} \left( 1 - \frac{4C^2}{n} \right) \quad (3.5)$$

For example, the estimator  $t_1 = \bar{y} + k \frac{s^2}{n \bar{y}^2} = \bar{y} + k u$ ,  $k$  being the characterizing scalar, has  $f_2' = k$ ,  $f_{12}'' = 0$  and  $\delta = 0$  so that it attains, for the optimum value  $f_2' = \mu(2 - \delta) = k$  satisfying (2.6) and giving  $k = 2\mu$ , the minimum mean square error given by (3.5).

- (d) The estimator like  $t_3$  has the practical advantage over the estimator like  $t_1$ , since the optimum value  $k = 1$  minimizing mean square error for  $t_3$  is independent of parameter whereas the optimum value  $k = 2\mu$  in case of  $t_1$  depends upon the parameter  $\mu$ . In fact, for the sub-set of estimators of the form  $t_3 = \bar{y}(u)$  of the class  $t$  where  $h(u)$  is the function of  $u$  such that  $h(0) = 1$ , there is no practical difficulty in using the optimum value  $f_2' = \mu h'(0) = \mu$  (the value of  $\delta$  for  $t_3$  is unity and  $h'(0)$  is the first derivative of  $h(u)$  with respect to  $u$  at  $u = 0$ ) giving  $h'(0) = 1$ , a quantity independent of the parameter.

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